Panasonic

Ultra High-Speed, High-Accuracy Laser Displacement Sensor

HL-C2 Series User's Manual

RS-232C Communication Control

WUME-HLC2RS-11

Preface

Thank you for purchasing Ultra High-Speed, High-Accuracy Laser Displacement Sensor "HL-C2 Series".

To fully use this product safely and properly, please read this manual carefully. See our Website (https://panasonic.net/id/pidsx/global) for the latest information about the product and latest user's manual.

Note

- 1. Please notice that illustrations in this manual might be little different from the actual product.
- 2. Contents of this manual will be changed without notice due to improvements.
- 3. This manual and software must not be partially or totally copied or reprinted.
- 4. If there are any questions, mistakes, paging disorder, or missing pages in this manual, please contact our sales office nearest you.
- 5. We have no responsibility of any results of operations regardless of the above.

Whole USER'S MANUAL Construction

The HL-C2 Series is prepared for the following user's manuals. Read them as necessary.

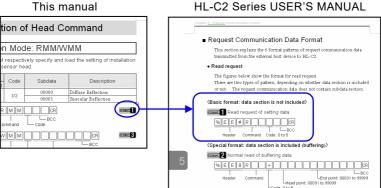
HL-C2 Series USER'S MANUAL (PDF)



It describes cautions for using HL-C2 Series, and installation method, operation method, function details, specifications, maintenance and inspection method of system components (controller, sensor head and compact console). It also describes the method of controlling the system by RS-232 communication.

See it for various communication formats.

The communication formats described in this manual ("HL-C2 Series USER'S MANUAL: RS-232C Communication Control") are explained in "HL-C2 Series USER'S MANUAL", too. Read it as necessary.



HL-C2 Series USER'S MANUAL

HL-C2 Series USER'S MANUAL: RS-232C Communication Control (PDF)



This manual It describes various commands for controlling the system by PLC or PC using RS-232C communication.

HL-C2 Series USER'S MANUAL: USB Communication Control (PDF)



This manual describes API for controlling the system by PLC or PC using USB communication.

HL-C2 Series USER'S MANUAL: Ethernet Communication Control (PDF)



This manual explains various settings to acquire measurement information of the HL-C2 system by PLC using Ethernet communication.

USER'S MANUAL for Intelligent Monitor AiM

The Intelligent Monitor AiM, which contains various useful functions in addition to the compact console, is available when developing PC-based system.

HL-C2 Series USER'S MANUAL: Intelligent Monitor AiM (PDF)



This manual is included as a PDF file in the Intelligent Monitor AiM, which can be downloaded on our Internet website.

This manual describes installation method, operation method, functional details and error messages of the software.

It also describes an evaluation analysis of HL-C2 Series or use of buffering function and received light intensity waveform display function, which are useful for optimum system setting. MEMO

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Manual Construction

	Preface	This chapter provides cautions for safe and correct operation of the product. Be sure to read this chapter.
1	Head Command	This chapter explains the commands for controlling the sensor head.
2	OUT Command	This chapter explains various commands for function settings regarding output data processing.
3	Common Command	This chapter explains the commands for function settings common in Head setting and OUT setting.
4	System Command	This chapter explains various commands for function settings regarding the system of equipment, such as initialization, save and communication settings.
5	Buffering Command	This chapter explains various commands for function settings and execution of operation regarding data buffering.
Appendix	Appendix	This chapter describes index and revision history.

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Safety Precautions

This product is intended to detect the objects and does not have the control function to ensure safety such as accident prevention.

Do not use the product as a sensing device to protect human body. Please use the products that comply with local laws and standards for human body protection specified by e.g., OSHA, ANSI and IEC.

Please read this manual carefully before using the product and use it correctly.

Symbol Indications

This manual uses symbols to indicate safety precautions, instructions, and reference.

Before reading this manual, fully understand the meanings of these indications.

∕ ₩ARN I NG	"WARNING" indicates the possibility that death or serious injury could result if a handling error occurs.	
▲CAUTION	"CAUTION" indicates the possibility that the user could be injured or property could be damaged if a handling error occurs.	
CHECK	"CHECK" indicates any instructions or precautions for using the system.	

∆WARN I NG

- Install a fail-safe device when the product is used for the purpose that has a possibility of physical injury or serious extended damage.
- Do not use the product in the atmosphere of flammable gas, to prevent explosion.

▲ CAUTION

- Use the product within specifications. Abnormal heat or smoke generation may occur.
- Do not disassemble or remodel the product. Electrical shock or smoke generation may occur.
- Connect the electric wire securely with the terminal screws. Imperfect connection may cause abnormal heat or smoke generation.
- Do not touch the terminal during energization of the product, to prevent electrical shock.

For Correct Use

This manual describes various commands for controlling the HL-C2 system by RS-232C communication.

For the detailed description of each function and communication format on the system, refer to "HL-C2 Series USER'S MANUAL" (separate volume).

Correct Handling

For the items listed below, refer to "HL-C2 Series USER'S MANUAL" (separate volume).

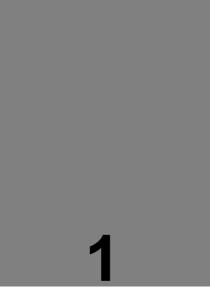
- Installation Environment
- Use Environment
- · Measures to Noise
- Warming Up Time
- Insulation Resistance and Voltage Resistance
- Power Supply
- Instantaneous Power Failure
- Grounding
- Installation

Cautions on Handling Laser Light

Refer to "HL-C2 Series USER'S MANUAL".

Standards

Refer to "HL-C2 Series USER'S MANUAL".



Head Command

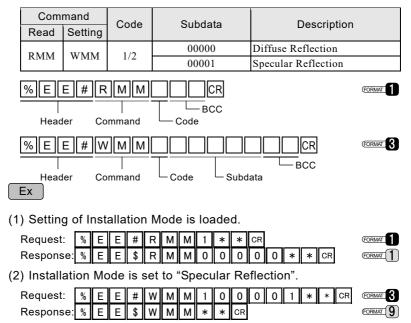
This chapter explains the commands for controlling the sensor head.

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1-1 Explanation of Head Command

1-1-1 Installation Mode: RMM/WMM

WMM and RMM respectively specify and load the setting of installation mode for each sensor head.



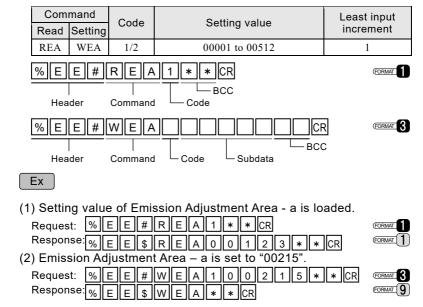
1-1-2 Emission Adjustment: RFB/WFB

WFB and RFB respectively specify and load the setting of emission adjustment for each sensor head.

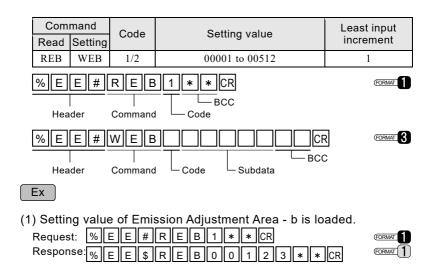
Command		Code	Subdata	Description
Read	Setting	Code	Subuala	Description
	WFB	FB 1/2	00000	Auto
			00001	0.04% Fixed
			00002	0.05% Fixed
RFB			00003	0.06% Fixed
			00004	0.08% Fixed
			00005	0.11% Fixed
			00006	0.14% Fixed

Read Setting Code Subdata Description Read Setting 00007 0.18% Fixed 00008 0.24% Fixed 00009 0.31% Fixed 000010 0.40% Fixed 00011 0.33% Fixed 00011 0.33% Fixed 00011 0.53% Fixed 00011 0.53% Fixed 00012 0.68% Fixed 00011 1.50% Fixed 00016 1.95% Fixed 00015 1.50% Fixed 00016 1.95% Fixed 00017 2.54% Fixed 00017 2.54% Fixed 00012 5.88% Fixed 00020 5.88% Fixed 00020 5.88% Fixed 00021 7.25% Fixed 00022 9.43% Fixed 00021 7.25% Fixed 00022 9.43% Fixed 00023 12.3% Fixed 00022 9.43% Fixed 00026 26.9% Fixed 00027 35.0% Fixed 00026 26.9% Fixed 00027 35.0% Fixed 00028 9.2% Fixed 00027 35.0% Fixed 00031 100% Fixed 00031 00031	Com	mand	Codo	Subdata	Deparintion	
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RFB WFB 1/2 00017 2.54% Fixed 00018 3.30% Fixed 00019 4.29% Fixed 00020 5.58% Fixed 00021 7.25% Fixed 00021 7.25% Fixed 00022 9.43% Fixed 00022 9.43% Fixed 00023 12.3% Fixed 00023 12.3% Fixed 00024 15.9% Fixed 00025 20.7% Fixed 00026 26.9% Fixed 000028 45.5% Fixed 00029 59.2% Fixed 000029 59.2% Fixed 00031 100% Fixed 000031 100% Fixed 00031 100% Fixed % E E # R F B CCR BCC BCC Header Command Code Subdata EX) Setting of Emission Adjustment is loaded. Request: % E E \$ R F B 1 * * CR Commit () E mission Adjustment is set to "100% Fixed". Request: % E E # W F B 0 0 0 0 0 * * CR Commit				00015	1.50% Fixed	
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00025 20.7% Fixed $00026 26.9% Fixed$ $00027 35.0% Fixed$ $00028 45.5% Fixed$ $00029 59.2% Fixed$ $00030 76.9% Fixed$ $00031 100% Fixed$ $00031 100% Fixed$ $00031 100% Fixed$ $00031 CR CR CR$ $Header Command Code Code$ $0% E E # W F B CC C C CR$ $F B C C C C C C CR$ $C C C C C C C C CR$ $C C C C C C C C C C C C C C C C C C C$				00023	12.3% Fixed	
$00026 26.9\% Fixed$ $00027 35.0\% Fixed$ $00028 45.5\% Fixed$ $00029 59.2\% Fixed$ $00030 76.9\% Fixed$ $00031 100\% Fixed$ $00031 100\% Fixed$ $00031 100\% Fixed$ $00031 CR CR CR$ $Header Command Code Subdata$ Ex $Setting of Emission Adjustment is loaded.$ $Request: \begin{tabular}{lllllllllllllllllllllllllllllllllll$				00024	15.9% Fixed	
00027 35.0% Fixed $00028 45.5% Fixed$ $00029 59.2% Fixed$ $00030 76.9% Fixed$ $00031 100% Fixed$ $000031 100% Fixed$ $000000 0 0 1 1 % CR COMM$				00025	20.7% Fixed	
00028 45.5% Fixed $00029 59.2% Fixed$ $00030 76.9% Fixed$ $00031 100% Fixed$ $000031 100% Fixed$				00026	26.9% Fixed	
00029 59.2% Fixed $00030 76.9% Fixed$ $00031 100% Fixed$ $% E E # R F B C C C C C C C C C C C C C C C C C C$				00027	35.0% Fixed	
00030 76.9% Fixed $00031 100% Fixed$ $% E E # R F B CR$ $Header Command Code$ $% E E # W F B C CR$ $Header Command Code Subdata$ Ex $Setting of Emission Adjustment is loaded.$ $Request: % E E # R F B 1 * * CR$ $Response: % E E $ R F B 0 0 0 0 0 * * CR$ $Command Code Subdata$ Ex $Setting of Emission Adjustment is loaded.$ $Request: % E E # R F B 1 * * CR$ $Response: % E E $ R F B 0 0 0 0 0 * * CR$ $Command Code Subdata$				00028	45.5% Fixed	
00031 100% Fixed $% E E # R F B CR$ $Header Command Code$ $% E E # W F B C CR$ $Header Command Code Subdata$ Ex $Setting of Emission Adjustment is loaded.$ $Request: % E E # R F B 1 * * CR$ $Response: % E E $ R F B 0 0 0 0 0 * * CR$ $Command Code Subdata$ Ex $Setting of Emission Adjustment is loaded.$ $Request: % E E # R F B 1 * * CR$ $Response: % E E $ R F B 0 0 0 0 0 * * CR$ $Command Code Subdata$				00029	59.2% Fixed	
$\frac{\% E E \# R F B}{Header Command Code}$ $\frac{\% E E \# W F B}{Header Command Code}$ $\frac{\% E E \# W F B}{Header Command Code}$ $\frac{\% E E \# W F B}{Header Command Code Subdata}$ $\frac{Ex}{Becc}$ $\frac{\% E E \# R F B}{B 1 * * CR}$ $\frac{\% E E \# R F B}{COMmand Code Subdata}$ $\frac{1}{COMmand Code Sub$						
Header Command Code $\bigcirc E E \# W F B$ CR Header Command Code $\bigcirc E E \# W F B$ CR Header Command Code Subdata Ex) Setting of Emission Adjustment is loaded. Request: $\bigcirc E E \# R F B 1 * * CR$ Response: $\bigcirc E E \$ R F B 0 0 0 0 0 * * CR$ $\bigcirc E E \$ R F B 0 0 0 0 0 * * CR$ $\bigcirc E E \# W F B 1 0 0 0 3 1 * * CR$ Request: $\bigcirc E E \# W F B 1 0 0 0 3 1 * * CR$				00031	100% Fixed	
Header Command Code $\bigcirc E E \# W F B$ CR Header Command Code $\bigcirc E E \# W F B$ CR Header Command Code Subdata Ex) Setting of Emission Adjustment is loaded. Request: $\bigcirc E E \# R F B 1 * * CR$ Response: $\bigcirc E E \$ R F B 0 0 0 0 0 * * CR$ $\bigcirc E E \$ R F B 0 0 0 0 0 * * CR$ $\bigcirc E E \# W F B 1 0 0 0 3 1 * * CR$ Request: $\bigcirc E E \# W F B 1 0 0 0 3 1 * * CR$	% E					(FORMAT
HeaderCommandCode $\begin{tabular}{lllllllllllllllllllllllllllllllllll$				====		
$\frac{\% E E \# W F B}{Header Command Code Subdata} CR CR CR BCC$	 	dor C	ommand			
Header Command Code Subdata Ex) Setting of Emission Adjustment is loaded. Request: % E E # R F B 1 * * CR COMMENT Response: % E E \$ R F B 0 0 0 0 0 * * CR COMMENT P:) Emission Adjustment is set to "100% Fixed". Request: % E E # W F B 1 0 0 0 3 1 * * CR COMMENT	nead		ommanu	Code		
Header Command Code Subdata Ex) Setting of Emission Adjustment is loaded. Request: % E E # R F B 1 * * CR COMMENT Response: % E E \$ R F B 0 0 0 0 0 * * CR COMMENT P:) Emission Adjustment is set to "100% Fixed". Request: % E E # W F B 1 0 0 0 3 1 * * CR COMMENT	% E	E # V	/ F B			(FORMAT 3
Header Command Code Subdata Ex) Setting of Emission Adjustment is loaded. Request: % E E # R F B 1 * * CR COMMET Response: % E E \$ R F B 0 0 0 0 0 * * CR COMMET Period 2) Emission Adjustment is set to "100% Fixed". COMMET Request: % E E # W F B 1 0 0 0 3 1 * * CR COMMET						_
) Setting of Emission Adjustment is loaded. Request: <u>% E E # R F B 1 * * CR</u> Response: <u>% E E \$ R F B 0 0 0 0 0 * * CR</u> 2) Emission Adjustment is set to "100% Fixed". Request: <u>% E E # W F B 1 0 0 0 3 1 * CR</u> COMMENT	Head	der C	ommand			
Request: % E E # R F B 1 * CR CORMET Response: % E E \$ R F B 0 0 0 0 * * CR CORMET CORMET CORMET CORMET CORMET 1 P: E Set to "100% Fixed". Request: % E E # W F B 1 0 0 3 1 * CR CORMET <						
Response: % E E R F B 0 0 0 0 * CR COMMET 2) Emission Adjustment is set to "100% Fixed". Request: % E # W F B 1 0 0 3 1 * CR COMMET 3	1) Settin	g of Em	ission Ac	ljustment is load	ed.	
Response: % E E R F B 0 0 0 0 * * CR COMME 1 2) Emission Adjustment is set to "100% Fixed". Request: % E # W F B 1 0 0 3 1 * CR COMME 3 3 3 1 * CR COMME 3	Request	t: % E	E # F	R F B 1 * *	CR	(FORMAT
Request: % E E # W F B 1 0 0 0 3 1 * * CR @@##T			E \$ F	R F B 0 0 0	00**CR	FORMAT 1
	•		istment i	s set to "100% F	ixed".	
	Request	t: % E	E # V	V F B 1 0 0	0 3 1 * * CR	(FORMAT 3
Response: % E E \$ W F B * * CR CORMAT 9			E \$ V	V F B * * CF		FORMAT 9

1-1-3 Emission Adjustment Area - a : REA/WEA



1-1-4 Emission Adjustment Area - b : REB/WEB



(2) Emission Adjustment Area - b is set to "00215".

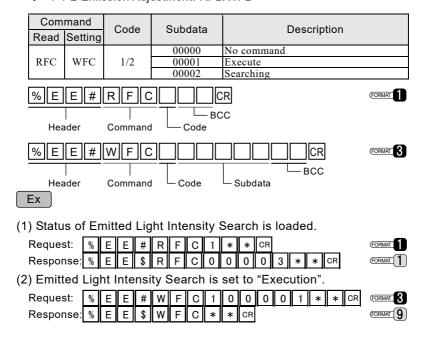
· .	,		-														
	Request:	%	Е	Е	#	W	Е	В	1	0	0	2	1	5	*	*	CR
	Response:	%	Е	Е	\$	W	Е	В	*	*	CR						



1-1-5Emitted Light Intensity Search: RFC/WFC

WFC automatically adjusts the emitted light intensity for each sensor head.

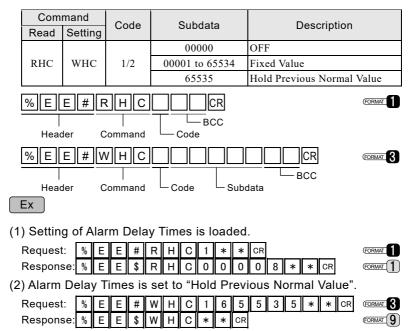
During command execution, the status of command execution can be loaded. After command execution, the value can be loaded by "Emission Adjustment". → "1-1-2 Emission Adjustment: RFB/WFB"



1-1-6 Alarm Delay Times: RHC/WHC

WHC and RHC respectively specify and load the setting of alarm delay times for each sensor head.

The setting here is reflected in digital measurement value, analog output, alarm terminal output and alarm indicator on the controller.

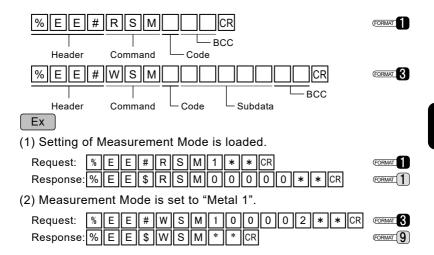


1-1-7 Measurement Mode: RSM/WSM

WSM selects the optimum digital processing mode to the object to be measured.

By selecting the optimum measurement algorithm such as disturbance correction of received light waveform, steady measurement values can be acquired.

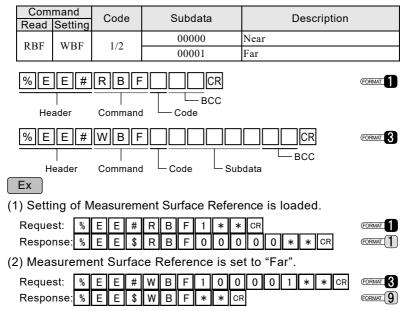
Com	mand	Code	Subdata	Description
Read	Setting	Code	Subuata	Description
			00000	Diffuse [Standard]
			00001	Specular[Standard]
			00002	Metal 1
RSM	WSM	1/2	00003	Metal 2
			00004	Penetration
			00005	Glass
			00006	Glass Pattern



1-1-8 Measurement Surface Reference: RBF/WBF

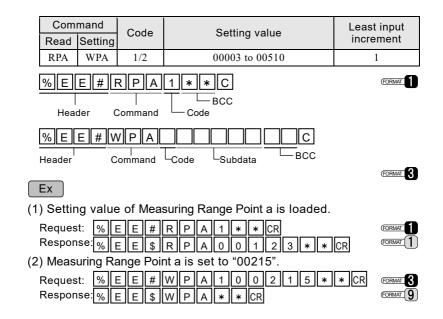
WBF and RBF respectively specify and load the setting of reference surface used for measurement for each sensor head.

It selects whether the measurement surface is counted from the near point of sensor head (Near) or from the far point (Far).



1-1-9 Measuring Range (a): RPA • WPA

A given range can be specified for measurement.



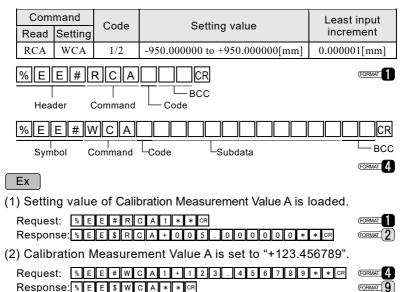
1-1-10 Measuring Range (b): RPB•WPB

Com	mand	Code	Setting value	Least input
Read	Setting	-	5	increment
RPB	WPB	1/2	00003 to 00510	1
%E	E # F	R P B		(FORMAT.
Hea	der (Command	L Code	
%E Hea	E # V der C	V P B	C Code L _{Subdata}	
Ex				FORMAT 3
(1) Settii	ng value	e of Mea	suring Range Point b is loaded.	
Reques Respor		E E # E E \$	R P A 1 * * CR R P B 0 0 1 2 3 * *	FORMAT 1 CR

1-1-11 Calibration Measurement Value A: RCA/WCA

WCA and RCA respectively specify and load the setting of calibration measurement value A for each sensor head.

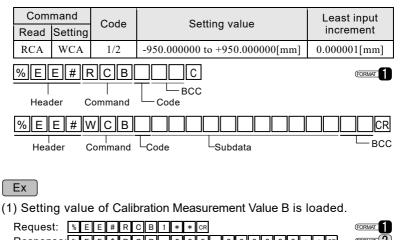
For the execution procedures of calibration, refer to "1-1-11 Execute Calibration: WCE".



1-1-12 Calibration Measurement Value B: RCB/WCB

WCB and RCB respectively specify and load the setting of calibration measurement value B for each sensor head.

For the execution procedures of calibration, refer to "1-1-11 Execute Calibration: WCE".

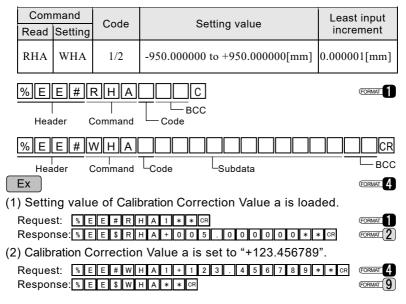


Response:	%	E	E	\$	R	С	В	-	0	0	5		0	0	0	0	0	0	*	*	CR			1
(2) Calibrati	on	N	lea	ası	ure	em	en	t۱	/al	ue	в	is	s	et	to	"_^	12:	3.4	-56	678	39'			
Request:	%	Е	Е	#	W	С	В	1	-	1	2	3		4	5	6	7	8	9	*	*	CR	FORMAT 4	J
Response:	%	Е	Е	\$	W	С	В	*	*	CR													FORMAT 9	J

1-1-13 Calibration Correction Value a: RHA/WHA

WHA and RHA respectively specify and load the setting of calibration correction value a for each sensor head.

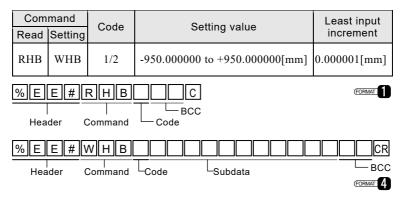
For the execution procedures of calibration, refer to "1-1-11 Execute Calibration: WCE".



1-1-14 Calibration Correction Value b: RHB/WHB

WHB and RHB respectively specify and load the setting of calibration correction value b for each sensor head.

For the execution procedures of calibration, refer to "1-1-11 Execute Calibration: WCE".



Ex

- (1) Setting value of Calibration Correction Value b is loaded.
 - Request: % E E # R H B 1 * * CR

Response: % E E \$ R H B - 0 0 5 . 0 0 0 0 0 * * cr



(2) Calibration Correction Value b is set to "-123.456789".

 Request:
 %
 E
 #
 W
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 1
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 9
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 cr
 Format
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 Response:
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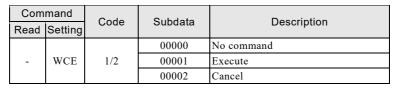
1-1-15 Execute Calibration: WCE

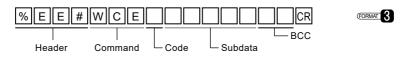
WCE executes and cancels the calibration for each sensor head.

Measurement Value A (mm) = Correction Value a (mm), Measurement Value B (mm) = Correction Value b (mm) Set any two points A and B to correction values.

Execution procedures of calibration

- 2 Set Measurement Value B. Refer to → "1-1-8".
- **3** Set Correction Value a. Refer to → "1-1-9".
- **4** Set Correction Value b. Refer to → "1-1-10".
- **5** Execute calibration by the WCE command.





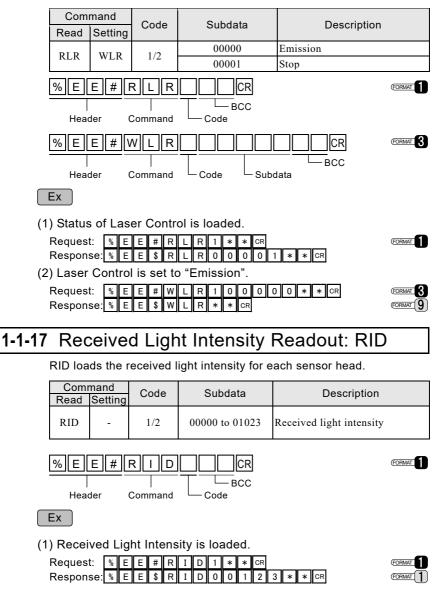
Ex

Calibration is executed.

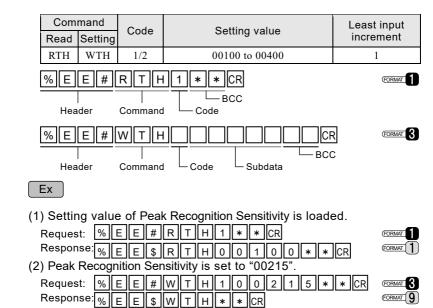
Request:	%	Е	Е	#	W	С	Е	1	0	0	0	0	1	*	*	CR	FORMAT 3
Response:	%	Е	Е	\$	W	С	Е	*	*	CR							FORMAT 9

1-1-16 Laser Control: RLR/WLR

WLR and RLR respectively specify and load the status of laser control for each sensor head.

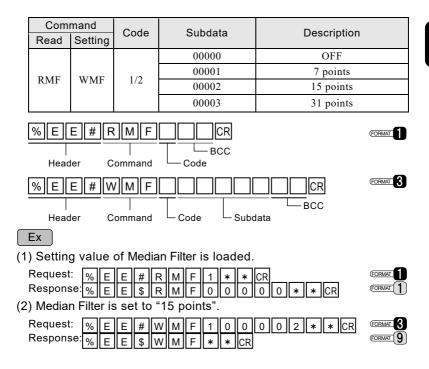


1-1-18 Peak Recognition Sensitivity: RTH/WTH

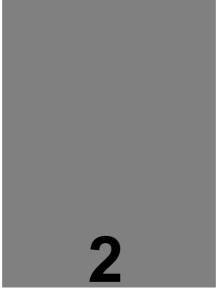


1-1-19 Median Filter RMF • WMF

Cut off changes in measurement values in order to prevent variation in measurement.



MEMO



OUT Command

This chapter explains various commands for function settings regarding output data processing.

2-1 Explanation of OUT Command ··· 2-2
2-1-1 Output Selection: ROS/WOS ····· 2-2
2-1-2 Transparent Object: RMN/WMN 2-3
2-1-3 Refractive Index Calculation:
RGK/WGK
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2-1-5 Zero Set: RZS/WZS2-5
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2-1-13 Operation Coefficient: RMK/WMK
2-1-14 Offset: RML/WML 2-12
2-1-15 Judgment Output Upper Limit
Value: RHL/WHL ······ 2-13
2-1-16 Judgment Output Lower Limit
Value: RLL/WLL······ 2-13
2-1-17 Judgment Output Upper Limit
Hysteresis: REH/WEH ······· 2-14
2-1-18 Judgment Output Lower Limit
Hysteresis: REL/WEL ······· 2-14

2-1-19	Analog Scaling Measurement
	Value A: RAH/WAH ······ 2-15
2-1-20	Analog Scaling Measurement
	Value B: RAL/WAL······ 2-16
2-1-21	Analog Scaling Voltage a: RVH/WVH2-16
	Analog Scaling Voltage b:
- ·	RVL/WVL······ 2-17
2-1-23	Execute Analog Scaling: WAS 2-18
	Analog Output at Alarm: RAA/WAA
2-1-24	
2 4 25	Analog Output at Alarm/ Fixed
Z-1-2J	Value: RFM/WFM ··········· 2-19
2-1-20	Analog Output at Data Unfixed:
	RDA/WDA
2-1-27	Digital Output at Alarm: RAD/WAD
	Alarm Output Delay: RAC/WAC2-21
2-1-29	Digit Number of Measurement
	Value: RKT/WKT ······ 2-22
	Measurement Value: RMD ····· 2-22
2-1-31	Alarm Output: ROA ······ 2-23
2-1-32	Strobe Output: ROB 2-23
2-1-33	Judgment Output HI: RHI ······ 2-24
2-1-34	Judgment Output GO: RGO ··· 2-24
	Judgment Output LO: RLO ····· 2-25

2

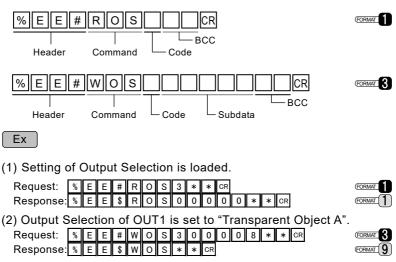
2-1 Explanation of OUT Command

2-1-1 Output Selection: ROS/WOS

WOS and ROS respectively specify and load the setting of output selection for each OUT.

Com	mand	Code	Subdata	Description
Read	Setting	Code	Subdata	Description
			00000	А
			00001	В
			00002	-A
			00003	-В
			00004	A+B
			00005	-(A+B)
			00006	A-B
ROS	wos	3/4	00007	B-A
RUS	wos	3/4	00008	Transparent Object A
			00009	Transparent Object B
			00010	Transparent Object -A
			00011	Transparent Object -B
			00012	[Transparent] A+B
			00013	[Transparent] -(A+B)
			00014	[Transparent] A-B
			00015	[Transparent] B-A

The default of OUT1 and OUT2 is "A" and "B" respectively.



2-1-2 Transparent Object: RMN/WMN

WMN and RMN respectively specify and load the setting of transparent object for each OUT.

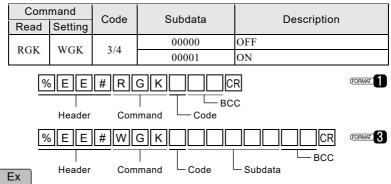
The commands are available while "Transparent Object" is selected in "Output Selection". Select the target surface(s) for measurement.

Com Read	mand Setting	Code	Subdata	Description									
			00000	1st Surface									
			00001	2nd Surface									
			00002	3rd Surface									
			00003	4th Surface									
			00004	Upper Limit Surface									
			00005	1st Surface - 2nd Surface									
			00006	1st Surface - 3rd Surface									
RMN	WMN	3/4	00007	1st Surface - 4th Surface									
			00008	1st Surface - Upper Limit Surface									
			00009	2nd Surface - 3rd Surface									
			00010	2nd Surface - 4th Surface									
			00011	2nd Surface - Upper Limit Surface									
			00012	3rd Surface - 4th Surface									
			00013	3rd Surface - Upper Limit Surface									
			00014	4th Surface - Upper Limit Surface									
%E		R M N	CR Code	(EORMAT									
%E Hea	% E E # W M N CR CR Header Command Code Subdata												
(1) Setti Reque Respo	st: %	ransparen E E # R E E \$ R	t Object is loaded M N 3 * * CR M N 0 0 0 0 0 0	FORMAT									
•	sparent st: %		set to "1st Surfac M N 3 0 0 0 0 M N * * CR	e - 4th Surface".									

2-1-3 Refractive Index Calculation: RGK/WGK

WGK and RGK respectively specify and load the setting of refractive index calculation for each OUT.

The commands are available while **"Transparent Object**" is selected in "Output Selection". Select if calculation of refractive index is executed or not.



(1) Setting of Refractive Index Calculation is loaded.





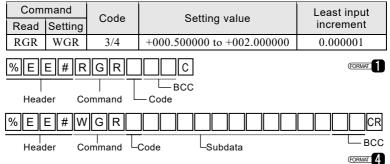
(2) Refractive Index Calculation is set to "ON".

Request:	%	Е	Е	#	W	G	К	3	0	0	0	0	1	*	*	CR	FORMAT 3
Response:	%	Ε	Е	\$	W	G	К	*	*	CR	\square						FORMAT 9

2-1-4 Refractive Index: RGR/WGR

WGR and RGR respectively specify and load the setting of refractive index for each $\ensuremath{\mathsf{OUT}}$.

The commands are available while "Transparent Object" is selected in "Output Selection" and "Refractive Index Calculation" is set to "ON".



Ex

(1) Setting value of Refractive Index is loaded.

Request: % E E # R G R 3 * * cR

Response: % E E \$ R G R + 0 0 1 . 0 0 0 0 0 * * cR



(2) Refractive Index is set to "+002.000000".

Request:												0	0	0	0	0	0	*	*	CR	(FORMAT 4
Response	%	E	E	\$	W	G	R	*	: ;	* (CR										FORMAT 9

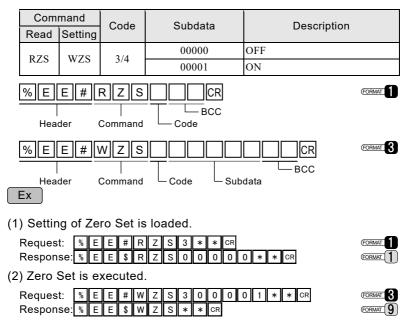
2-1-5 Zero Set: RZS/WZS

WZS and RZS execute and load the setting of zero set for each OUT.

After executing Zero Set, the measurement value will be set to zero.

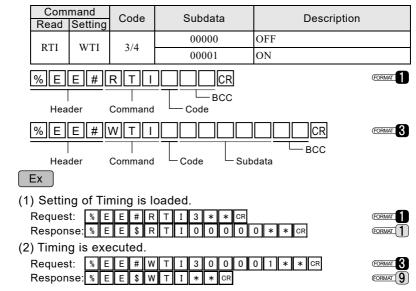
OCHECK

When a value other than 0 is specified as an offset value in "Offset", the measurement value will be the specified value.



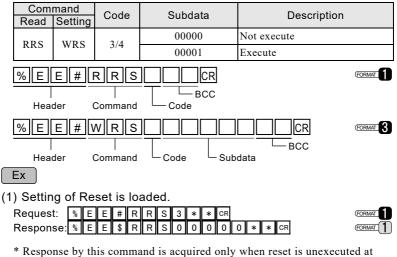
2-1-6 Timing: RTI/WTI

WTI and RTI execute and load the setting of timing for each OUT.



2-1-7 Reset: RRS/WRS

WRS and RRS execute and load the setting of reset for each OUT.



Response by this command is acquired only when reset is unexecuted a readout.

(FORMAT

FORMAT 9

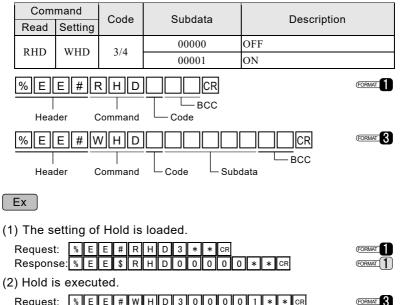
(2) Reset is executed.

 Request:
 %
 E
 #
 W
 R
 S
 3
 0
 0
 0
 1
 *
 *
 CR

 Response:
 %
 E
 E
 \$
 W
 R
 S
 *
 *
 CR

2-1-8 Hold: RHD/WHD

WHD and RHD execute and load the setting of hold.

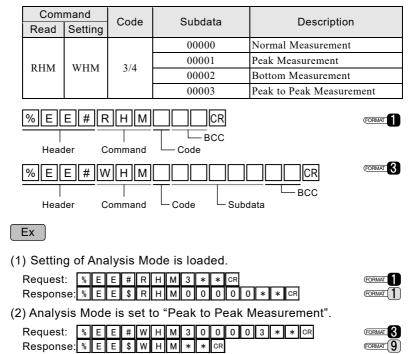


 Request:
 %
 E
 #
 W
 H
 D
 3
 0
 0
 0
 1
 *
 cr
 CORMAT
 3

 Response:
 %
 E
 E
 \$
 W
 H
 D
 *
 *
 cr
 CORMAT
 9
 CORMAT
 S
 CORMAT<

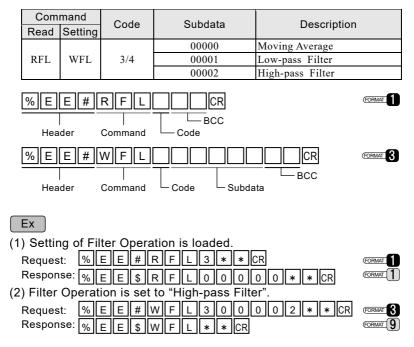
2-1-9 Analysis Mode: RHM/WHM

WHM and RHM respectively specify and load the setting of analysis mode for each OUT.



2-1-10 Filter Operation: RFL/WFL

WFL and RFL respectively specify and load the setting of filter operation for each OUT.



2-1-11 Average Times: RAV/WAV

WAV and RAV respectively specify and load the setting of average times for each OUT.

The commands are available while Moving Average is selected in "Filter Operation".

Com	mand	Code	Subdata	Description				
Read	Setting	Code	Subuala	Description				
			00000	1 time				
			00001	2 times				
			00002	4 times				
			00003	8 times				
			00004	16 times				
			00005	32 times				
			00006	64 times				
			00007	128 times				
RAV	WAV	3/4	00008	256 times				
			00009	512 times				
			00010	1024 times				
			00011	2048 times				
			00012	4096 times				
			00013	8192 times				
			00014	16384 times				
			00015	32768 times				
	00016 65536 times							
%E Hea		RAV Command	CR BCC Code	Q	FORMAT			
%E Hea		WAV Command	Code Subda		FORMAT			
Ex (1) Settir								
Reques Respon	1) Setting of Average Times is loaded. Request: % E E # R A V 3 * * CR Response: % E E \$ R A V 0 0 0 0 9 * * CR 2) Average Times is set to "4096 times".							
Reques Respon	st: % E	E # W	A V 3 0 0 0 1 A V * * CR	2 * * CR	FORMAT 3			

2

2-1-12 Cutoff Frequency: RCO/WCO

WCO and RCO respectively specify and load the setting of cutoff frequency for each OUT.

Com	Command		Sub	data		Description			
Read	Setting	Code	Sub	มลเล		Description			
			000	000		1[Hz]			
			000	01		2[Hz]			
			000	002		4[Hz]			
			000	003		10[Hz]			
			000	004		20[Hz]			
RCO	WCO	3/4	000	005		40[Hz]			
			000	06		100[Hz]			
			000	07		200[Hz]			
			000	08		400[Hz]			
			000	09		1000[Hz]			
			000	10		2000[Hz]			
% E # R C C CR COMMENT Header Command Code CCR COMMENT COMMENT % E # W C O C Header Command Code CCR COMMENT Header Command Code Subdata									
Ex (1) Setting of Cutoff Frequency is loaded. Request: % E E # R C O 3 * * CR									
Respon		$\dashv \square \square \square$	┥┝╧┥┝╧┥┝╧	┥┝═┥┝═		6 * * CR	FORMAT 1		
(2) Cutoff Frequency is set to "400[Hz]".									
Reques	st: % E	E # W	/ C O 3	0 0	0	0 8 * * CR	FORMAT 3		

Request:	%	Е	Е	#	W	С	0	3	0	0	0	0	8	*
Response:	%	Е	Е	\$	W	С	0	*	*	CR				

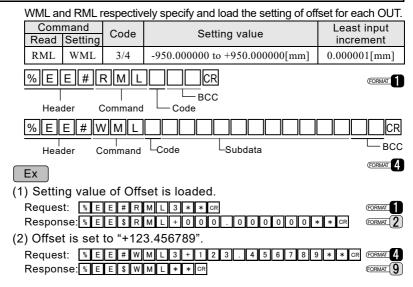


2-1-13 Operation Coefficient: RMK/WMK

WMK and RMK respectively specify and load the setting of operation coefficient for each OUT.

Comn Read	nand Setting	Code	Setting value	Least input increment					
RMK	WMK	3/4	+000.100000 to +009.999999	0.000001					
% E E # R M K CR Header Command Code									
% E E # W M K CR Header Code Subdata BCC									
(1) Setting Request Respons	Ex (1) Setting value of Operation Coefficient is loaded. Request: % E E # R M K 3 * * CR Response:% E E \$ R M K + 0 0 1 . 0 0 0 0 0 0 * * CR								
Request	(2) Operation Coefficient is set to "+001.500000". Request: %EE\$WMK3+001.500000**CR @Response:%EE\$WMK**CR @RMAT(9)								

2-1-14 Offset: RML/WML



2-1-15 Judgment Output Upper Limit Value: RHL/WHL

WHL and RHL respectively specify and load the setting of upper limit value of judgment output for each OUT.

value of judgment out								
Command Read Setting	Setting value	Least input increment						
RHL WHL 3/4	-950.000000 to +950.000000[mm]	0.000001[mm]						
%EE#RHL Header Command		(FORMAT 1						
Header Command Code Lsubdata								
Ex		(FORMAT 4						
	gment Output Upper Limit Valu	e is loaded						
Request: % E E #		(FORMAT						
Response: % E E \$ R		* * CR FORMAT						
(2) Judgment Output U	pper Limit Value is set to "+123	.456789".						
Request: <u>% E E # W</u>		9 * * CR (FORMAT 4						
Response: % E E \$	W H L * * CR	(<u>)</u>						
2-1-16 Judgment Output Lower Limit Value: RLL/WLL WLL and RLL respectively specify and load the setting of lower limit								
WLL and RLL respec	ively specify and load the settir	ng of lower limit						
value of judgment out	ively specify and load the settir out for each OUT.							
WLL and RLL respec value of judgment out Command Read Setting Code	ively specify and load the settir out for each OUT. Setting value	ng of lower limit Least input increment						
value of judgment out	out for each OUT.	Least input						
value of judgment out Command Read Setting	out for each OUT. Setting value	Least input increment						
value of judgment out Command Read Setting RLL WLL 3/4 % E E # R L L	Setting value -950.000000 to +950.000000[mm] CR BCC	Least input increment 0.000001[mm]						
value of judgment out <u>Command</u> Code <u>Read</u> Setting <u>RLL</u> WLL 3/4 <u>%</u> [E][#][R][L][Header Command	Setting value -950.000000 to +950.000000[mm] CR BCC	Least input increment 0.000001[mm]						
value of judgment out Command Read Setting RLL WLL 3/4 % E E # R L L	Setting value -950.000000 to +950.000000[mm] CR BCC	Least input increment 0.000001[mm]						
value of judgment out <u>Command</u> Code <u>Read</u> Setting <u>RLL</u> WLL 3/4 <u>%</u> [E][#][R][L][Header Command	Setting value -950.000000 to +950.000000[mm] CR BCC	Least input increment 0.000001[mm]						
value of judgment out Command Read Setting RLL WLL 3/4 % E E # R L L Header Command % E E # W L L	Setting value -950.000000 to +950.000000[mm] CR BCC Code	Least input increment 0.000001[mm]						
value of judgment out Command Read Setting RLL WLL 3/4 % E E # R L L Header Command % E E # W L L Header Command Ex	Setting value -950.000000 to +950.000000[mm] CR BCC Code	Least input increment 0.000001[mm]						
value of judgment out Command Read Setting RLL WLL 3/4 % E E # R L L Header Command % E E # W L L Header Command Ex (1) Setting value of Jud Request: <u>% E E # R</u>	Setting value -950.000000 to +950.000000[mm] CR Code Code Subdata Image: Code Subdata Image: Code Subdata	Least input increment 0.000001[mm] CORME CR BCC CORME 4 He is loaded.						
value of judgment out Command Read Setting RLL WLL 3/4 % E E # R L L Header Command % E E # W L L Header Command (1) Setting value of Jud Request: % E E # R Response: % E E \$ R	Setting value Setting value -950.000000 to +950.000000[mm] CR BCC Code Code Subdata gment Output Lower Limit Value L 3 * * 05 L 0 0 5 0 0 0 0 0 0 *	Least input increment 0.000001[mm] CORMAT 1 CORMAT 1 BCC CORMAT 4 He is loaded.						
value of judgment out Command Read Setting RLL WLL 3/4 % E E # R L L Header Command % E E # W L L Header Command Ex (1) Setting value of Jud Request: <u>S E E # R</u> Response: <u>S E E \$ R</u> (2) Judgment Output L	Setting value Setting value -950.000000 to +950.000000[mm] CR BCC Code Code Subdata gment Output Lower Limit Value L 3 * * CR L - 0 0 5 . 0 0 0 0 0 * ower Limit Value is set to "-123.	Least input increment 0.000001[mm] COMMAT 1 COMMAT 1 COMMAT 4 CR CR COMMAT 1 COMMAT						
value of judgment out Command Read Setting RLL WLL 3/4 % E E # R L L Header Command % E E # W L L Header Command (1) Setting value of Jud Request: % E E # R Response: % E E \$ R	Setting value -950.000000 to +950.000000[mm] -950.000000 to +950.000000[mm] CR BCC Code Code Subdata Image: Subdata I	Least input increment 0.000001[mm] CORMAT 1 CORMAT 1 BCC CORMAT 4 He is loaded.						

2-1-17 Judgment Output Upper Limit Hysteresis: REH/WEH

WEH and REH respectively specify and load the setting of upper limit hysteresis of judgment output for each OUT.

Command Code	e Setting value	Least input						
Read Setting REH WEH 3/4	+000.000000 to +950.000000[mm]	increment 0.000001[mm]						
%EE#REH								
		FORMAT						
Header Command								
Header Command	L _{Code} L _{Subdata}	└── BCC						
Ex		FORMAT 4						
(1) Setting value of Jud	gment Output Upper Limit Hyste	resis is loaded.						
Request: <u>% E E # R</u>		FORMAT						
Response: % E E \$ R								
	pper Limit Hysteresis is set to " E H 3 + 1 2 3 . 1 2 3 4 5 6							
Response: % E E \$ W		FORMAT 9						
2-1-18 Judgment Output	t Lower Limit Hysteresis:	REL/WEL						
	ively specify and load the setting	of lower limit						
Command	t output for each OUT.	Least input						
Read Setting Code	Setting value	increment						
REL WEL 3/4	+000.000000 to +950.000000[mm]	0.000001[mm]						
(FORMAT								
		FORMAT						
Header Command								
Header Command								
Header Command								
Header Command WEE#WEL Header Command Ex (1) Setting value of Jud	gment Output Lower Limit Hyste							
Header Command WEE#WEL Header Command Ex (1) Setting value of Jud Request: <u>KEE#R</u>	Gment Output Lower Limit Hyste	CR BCC COMME 4 Presis is loaded.						
Header Command WEE#WEL Header Command Ex (1) Setting value of Jud Request: <u>%EE#R</u> Response: <u>%EE\$R</u>	gment Output Lower Limit Hyste	CR CR CR CORMAT CR CORMAT CR CR CR CR CR CR CR CR CR CR						
Header Command WEE#WEL Header Command Ex (1) Setting value of Jud Request: <u>%EE#R</u> Response: <u>%EE\$R</u>	gment Output Lower Limit Hyster E L 3 * * 08 E L + 0 0 1 . 0 0 0 0 0 0 * power Limit Hysteresis is set to "	CR BCC FORMAT 4 Presis is loaded. FORMAT 1 * CR FORMAT 2						
Header Command WEE Header Command Ex (1) Setting value of Jud Request: SEE Response: SEE SR (2) Judgment Output Lo	Grade BCC Grade Subdata Code Subdata E 1 E 1 E 1 I 0	CR BCC CRAAT 4 Presis is loaded. CRAAT 1 CRAAT 2 CRAAT 2 CRAAT 2 CRAAT 2 CRAAT 2						

2-1-19 Analog Scaling Measurement Value A: RAH/WAH

WAH and RAH respectively specify and load the setting of analog scaling measurement value A.

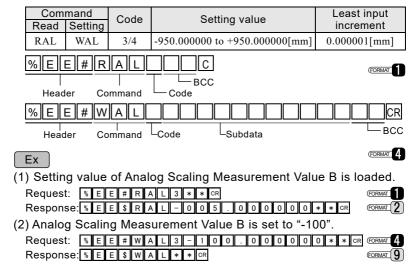
For the execution procedures of analog scaling, refer to \Rightarrow "2-1-20 Execute Analog Scaling: WAS".

	Com Read	mand Setting	Code	Setting value	Least input increment				
	RAH	WAH	3/4	-950.000000 to +950.000000[mm]	0.000001[mm]				
	% E	E # F	RAH						
	Header Command Code								
	% E	E # V	/ A H		CR				
	Header Command Code Subdata								
	Ex				FORMAT 4				
(1) Settir	ng value	e of Ana	alog Scaling Measurement Valu	e A is loaded.				
	Reques Respon	t: % E se:% E		A H 3 * * cr A H + 0 0 5 . 0 0 0 0 0 0 *	FORMAT				
	(2) Analog Scaling Measurement Value A is set to "100".								
	Reques Respon		E # W E \$ W	A H 3 + 1 0 0 . 0 0 0 0 0 0 C A H * * CR	ermat 9				

2-1-20 Analog Scaling Measurement Value B: RAL/WAL

WAL and RAL respectively specify and load the setting of analog scaling measurement value B.

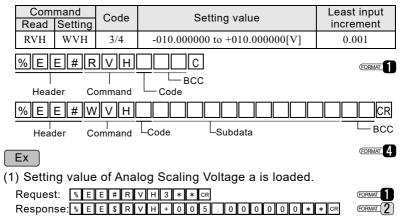
For the execution procedures of analog scaling, refer to \rightarrow "2-1-20 Execute Analog Scaling: WAS".



2-1-21 Analog Scaling Voltage a: RVH/WVH

WVH and RVH respectively specify and load the setting of analog scaling voltage a.

For the execution procedures of analog scaling, refer to \rightarrow "2-1-20 Execute Analog Scaling: WAS".



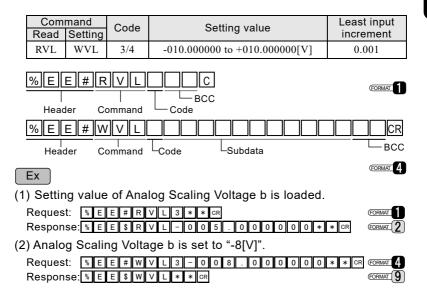
(2) Analog Scaling Voltage a is set to "8[V]".

 Request:
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2-1-22 Analog Scaling Voltage b: RVL/WVL

WVL and RVL respectively specify and load the setting of analog scaling voltage b.

For the execution procedures of analog scaling, refer to \rightarrow "2-1-20 Execute Analog Scaling: WAS".



2-1-23 Execute Analog Scaling: WAS

WAS executes respective analog scaling.

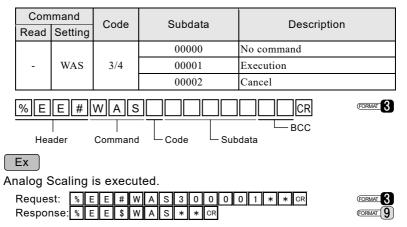
Measurement value A[mm] = a[V], Measurement value B[mm] = b[V]Set appropriate voltage to any two points A and B.

Execution procedures of analog scaling

- **1** Set Measurement Value A. Refer to \rightarrow "2-1-16".
- 2 Set Measurement Value B. Refer to → "2-1-17".
- **3** Set Voltage a. Refer to \rightarrow "2-1-18".
- 4 Set Voltage b. Refer to \rightarrow "2-1-19".
- **5** Execute analog scaling by the WAS command.

OCHECK

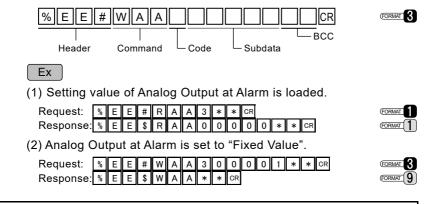
When analog scaling will be aborted during the procedures due to an abnormality such as communication error, make sure to transmit "Cancel" of the command.



2-1-24 Analog Output at Alarm: RAA/WAA

WAA and RAA respectively specify and load the setting of analog output at alarm for each OUT.

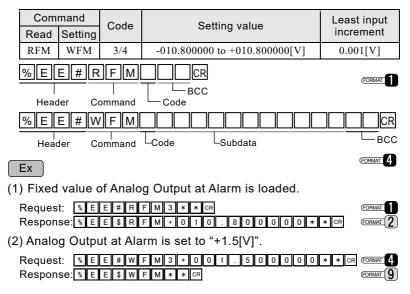
Com	Command		Subdata	Description		
Read	Setting	Code	Subuala	Description		
RAA	WAA	3/4	00000	Hold Previous Value		
KAA	WAA	3/4	00001	Fixed Value		
%E Hea	E # F	R A A			(FORMAT_	



2-1-25 Analog Output at Alarm/ Fixed Value: RFM/WFM

WFM and RFM respectively specify and load the setting of fixed value of analog output at alarm for each OUT.

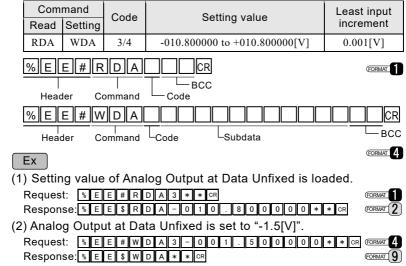
The commands are available while "Fixed Value" is selected in "Analog Output at Alarm".



2-1-26 Analog Output at Data Unfixed: RDA/WDA

WDA and RDA respectively specify and load the setting of analog output at data unfixed for each OUT.

Analog output at data unfixed can be specified arbitrarily. The digital measurement value at data unfixed is "-999.9999999".



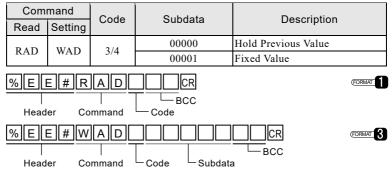
2-1-27 Digital Output at Alarm: RAD/WAD

WAD and RAD respectively specify and load the setting of digital output at alarm for each OUT.

It is the setting related to digital output at alarm.

When "Fixed Value" is selected, the setting value is "+999.999999".

When "Hold Previous Value" is selected, the value previously held at normal status is displayed.



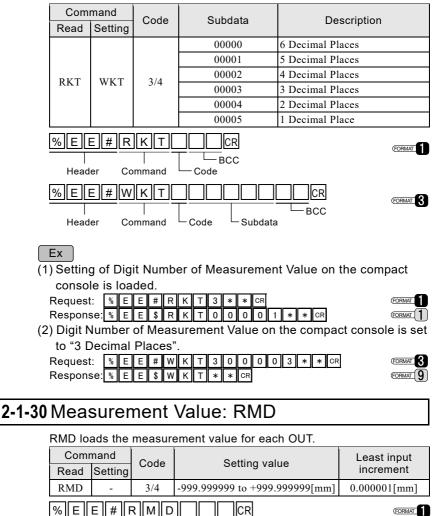
Ex (1) Setting of Digital Output at Alarm is loaded. Request: |% | E | E | # | R | A | D | 3 * * CR FORMAT Response: % E E S R A D 0 0 0 * CR 0 1 * FORMAT (2) Digital Output at Alarm is set to "Hold Previous Value". Request: |% E E # W A D 3 0 0 0 0 0 * * CR (FORMAT Response: % FORMAT 9 Е Е \$ D W A * * CR 2-1-28 Alarm Output Delay: RAC/WAC WAC and RAC respectively specify and load the setting of alarm output delay for each OUT. While the setting is OFF, an alarm is output to the alarm output terminal in real time at alarm, regardless of the setting in "Alarm Delay Times".

Com Read	mand Setting	Code	Subdata	Description				
RAC	WAC	3/4	00000	OFF				
inte	inte	5/-1	00001	ON				
Head	Header Command Code							
% E E # W A C CR Header Command Code Subdata								
Ex (1) Settin	a of Ala	rm Qutn	ut Delay is loade	ч				
Request	~				(FORMAT			
Respons		┪━━┩┝━━┩┝	R A C 0 0 0	0 1 * * CR	FORMAT			
(2) Alarm Output Delay is set to "OFF".								
Request	t: % E	E #	WAC300000**CR					
Respons	se: % E	E \$	WAC**CR]	FORMAT 9			

2-1-29 Digit Number of Measurement Value: RKT/WKT

WKT and RKT respectively specify and load the setting of digit number of measurement value displayed on the compact console for each OUT.

The command specifies the number of digits displayed after decimal point on the compact console at the measurement using the measurement value that consists of "1-character symbol + 3-character integral part + decimal point + 5-character decimal part". The setting has six choices shown below.



Code

Header

Command

-BCC

Ex

Setting value of OUT1 Measurement Value is loaded.

 Request:
 %
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 CR
 CORMAT

 Response:
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 9
 *
 *
 CR

2-1-31 Alarm Output: ROA

ROA loads the status of alarm output for each OUT.

Com	mand	Code	Subdata	Description						
Read	Setting	Code	Subuata							
			00000	No alarm output (OFF)						
		3/4	00001	Measurement alarm output						
ROA	_		00005	Sensor head A unconnected						
			00006	Connection head unadapted						
			00007	Head connection check error						
	% E # R O A CR Header Command Code Code									

Ex

Status of Alarm Output is loaded.

Request:	%	Е	Е	#	R	0	А	3	*	*	CR				
Response:	%	Е	Е	\$	R	0	А	0	0	0	0	1	*	*	CR

2-1-32 Strobe Output: ROB

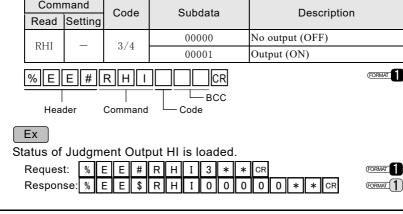
ROB loads the status of strobe output for each OUT.

Command		Code	Subdata	Description					
Read	Setting	Code	Subuala	Description					
ROB		3/4	00000	No strobe output (OFF)					
KOB		5/4	00001	Strobe output (ON)					
% E # R O B CR % E E # R O B CR Header Command Code Code Command Code									
Ex atus of §	Strobe (Output is	loaded.						
Request: Respons		E # F E \$ F	╧╫╧╌╫╧╌╫╼╾╢	CR FORMAT I 0 1 * * CR FORMAT I					

(FORMAT

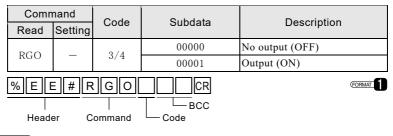
2-1-33 Judgment Output HI: RHI

RHI loads the status of judgment output HI for each OUT.



2-1-34 Judgment Output GO: RGO

RGO loads the status of judgment output GO for each OUT.



Ex

Status of Judgment Output GO is loaded.

Request:	%	Е	Е	#	R	G	0	3	*	*	CR					(FORMAT
Response:	%	Е	Е	\$	R	G	0	0	0	0	0	1	*	*	CR	(FORMAT 1

2-1-35 Judgment Output LO: RLO

RLO loads the status of judgment output LO for each OUT.

nand	Codo	Subdata	Description	
Setting	Code	Subuala	Description	
	2/4	00000	No output (OFF)	
	3/4	00001	Output (ON)	
= # F	R L O		(FORMAT)	O
-	<u> </u>	BCC		
er C	ommand	- Code		
	Setting —	Setting Code - 3/4	Code Subdata - 3/4 00000	Code Subdata Description - 3/4 00000 No output (OFF) - 3/4 00001 Output (ON)

Ex

Status of Judgment Output LO is loaded.

Request:	%	Е	Е	#	R	L	0	3	*	*	CR				FORMAT
Response:	%	Ε	Е	\$	R	L	0	0	0	0	0	0	*	* CR	FORMAT 1

MEMO

3

Common Command

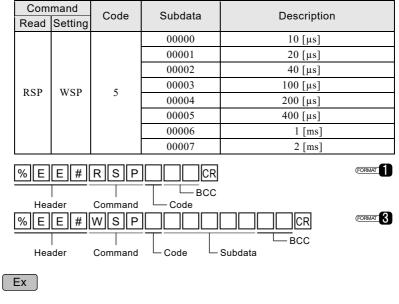
This chapter explains the commands for function settings common in Head setting and OUT setting.

3-1 Explanation of Common Command	
3-1-1 Sampling Cycle: RSP/WSP	3-2
3-1-2 Terminal Input Control: RIM/WIM	3-3
3-1-3 Chattering Prevention for Terminal Input:	
RIC/WIC	3-3
3-1-4 Judgment Output Off Delay: ROF/WOF ···	3-4
3-1-5 Interference Prevention: RXT/WXT	3-5
3-1-6 2 Output Measurement Value: RMA	3-5
3-1-7 All Output Read: RMB	3-6

3-1 Explanation of Common Command

3-1-1 Sampling Cycle: RSP/WSP

WSP and RSP respectively specify and load the setting of sampling cycle.



(1) Setting of Sampling Cycle is loaded.

Request:	%	Е	Е	#	R	S	Ρ	5	*	*	CR					FORMAT
Response:	%	Ε	Е	\$	R	S	Ρ	0	0	0	0	2	*	*	CR	FORMAT 1

(2) Sampling Cycle is set to "2[ms]".

Request: %	E	Е	#	W	S	Ρ	5	0	0	0	0	7	*	*	CR	FORMAT 3
Response: %	Е	Е	\$	W	S	Ρ	*	*	CR							FORMAT 9

OCHECK

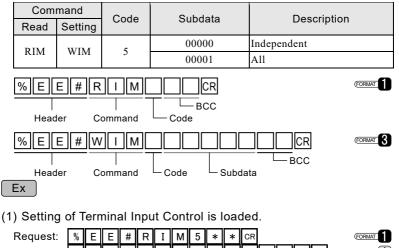
If this setting is changed between $10\mu s \leftrightarrow 20\mu s$ or above, the USB of the controller will be reset. To continuously use the USB device after such changes, reconnect following the USB device Close and Open procedures.

REFERENCE

USB Close Function : HLC2_Close() USB Open Function : HLC2 OpenByIndex(), HLC2 Open()

3-1-2 Terminal Input Control: RIM/WIM

WIM and RIM respectively specify and load the setting of terminal input control.



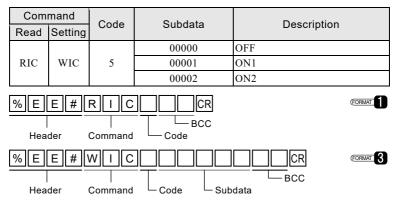
Request:	%	E	E	#	к	1	M	5	*	*	CR					(FORMAT
Response:	%	Е	Е	\$	R	Ι	М	0	0	0	0	0	*	*	CR	FORMAT 1

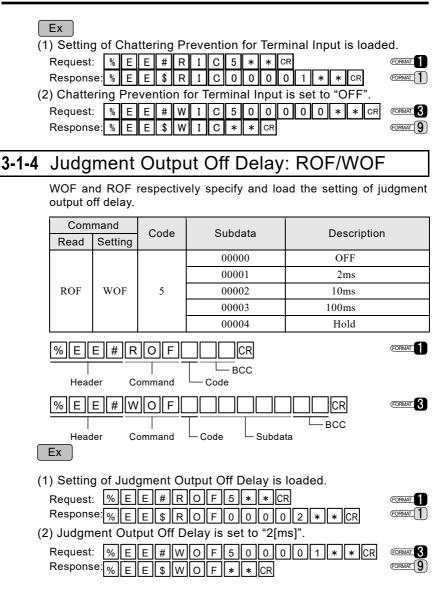
(2) Terminal Input Control is set to "All".

Request:	%	E	Е	#	W	Ι	М	5	0	0	0	0	1	*	*	CR	FORMAT 3
Response:	%	Ε	Е	\$	W	Ι	М	*	*	CR							FORMAT 9

3-1-3 Chattering Prevention for Terminal Input: RIC/WIC

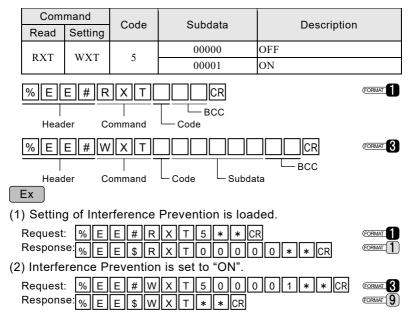
WIC and RIC respectively specify and load the setting of chattering prevention for terminal input.





3-1-5 Interference Prevention: RXT/WXT

WXT and RXT respectively specify and load the setting of interference Prevention.

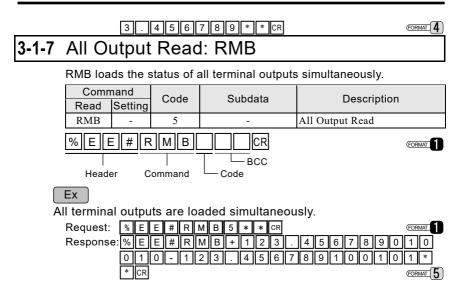


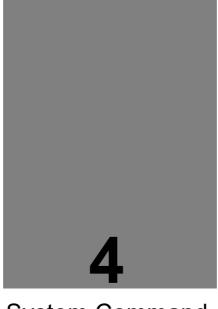
3-1-6 2 Output Measurement Value: RMA

RMA loads the measurement value of OUT1 and OUT2 at the same time.

Use the RMD command to separately load the measurement value for OUT1 and OUT2. →"2-1-27 Measurement Value: RMD".

Comn	nand	Code	Subdata	Description
Read	Setting	Code	Subuala	Description
RMA	-	5	-	-999.9999999 to +999.999999[mm] Measurements simultaneous reading of OUT1 / OUT2.
% E E	E # R	MA		FORMAT
			BCC	
Head	er C	ommand	Code	
Ex				
1) Measu	rement	value of C	OUT1 and OUT2 a	are loaded at the same time.
Request:	% E	E # R I	M A 5 * * CR	FORMAT
Respons	e: % E	E # R I	MA+123.	4 5 6 7 8 9 - 1 2





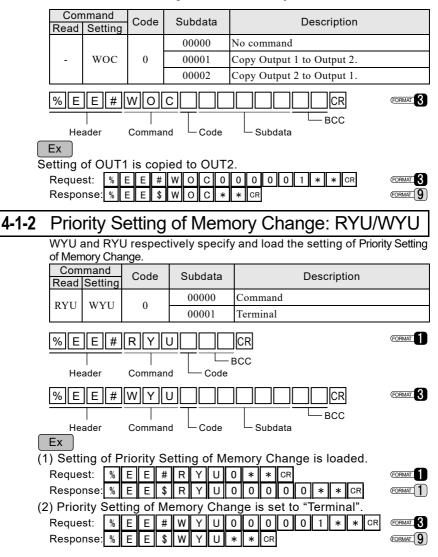
System Command

This chapter explains various commands for function settings regarding the system of equipment, such as initialization, save and communication settings.

4-1 Explanation of System Command

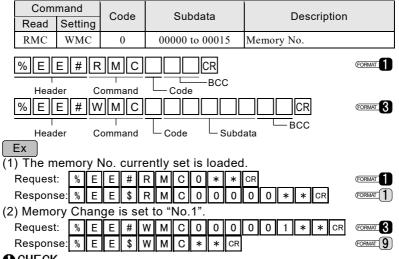
4-1-1 Copy Output Setting: WOC

WOC copies the setting of OUT1 or OUT2 to the other OUT. In the memory No. selected in "Memory Change", the command copies the setting of OUT to the other (from OUT1 to OUT2 or from OUT2 to OUT1). However, Zero Set, Timing and Reset are not copied.



4-1-3 Memory Change: RMC/WMC

WMC and RMC respectively specify and load the setting of Memory Change. Up to 16 settings can be saved.



OCHECK

If a memory switchover which changes the sampling cycle setting to more than $10\mu s \leftrightarrow 20\mu s$ is executed, the USB of the controller will be reset. To continuously use the USB device after such a memory switchover, reconnect following the USB device Close and Open procedures.

REFERENCE

USB Close Function : HLC2_Close()

USB Open Function : HLC2_OpenByIndex(), HLC2_Open()

4-1-4 Copy Source Memory: WSF

WSF specifies the memory number of copy source.

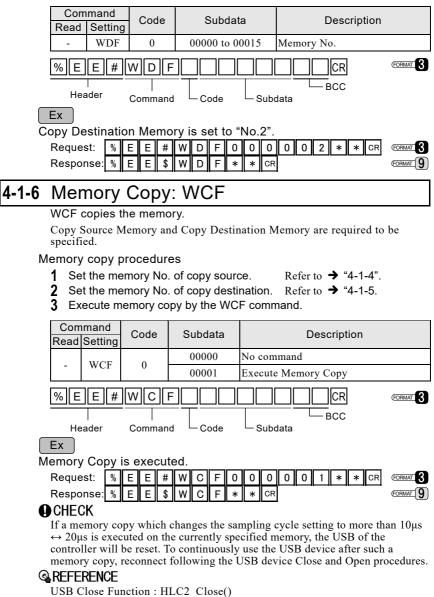
For the memory copy procedures, refer to \rightarrow "4-1-6 Memory Copy: WCF".

	Com Read	mand Setting	Code	Subdata	Description
	Read	Setting			
	-	WSF	0	00000 to 00015	Memory No.
	% E	E #	WSF		
	Hea	ader	Command	└─ Code └─ Sub	data
	Ex				
С	opy So	urce Me	emory is	set to "No.1".	
	Reques	st: %	E E #	W S F 0 0 0	0 0 1 * * CR FORMAT 3
	Respor	nse: %	E E \$	WSF**CF	(FORMAT 9

4-1-5 Copy Destination Memory: WDF

WDF specifies the memory number of copy destination.

For the memory copy procedures, refer to \rightarrow "4-1-6 Memory Copy: WCF".

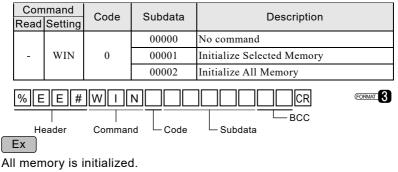


USB Open Function : HLC2 OpenByIndex(), HLC2 Open()

4-1-7 Initialize: WIN

WIN initializes the memory.

The command resets the status of selected memory No. to factory default. For the detail of "Selected Memory No.", refer to \rightarrow "4-1-3 Memory Change: RMC/WMC".



Request:	%	Е	Е	#	W	Ι	Ν	0	0	0	0	0	2	*	*	CR	(FORMAT 3
Response:	%	Е	Е	\$	W	Ι	Ν	*	*	CR							FORMAT 9

OCHECK

If the setting initialization is executed while the sampling cycle of the controller is set to 10 μ s, the USB of the controller will be reset. To continuously use the USB device after the setting initialization, reconnect following the USB device Close and Open procedures.

REFERENCE

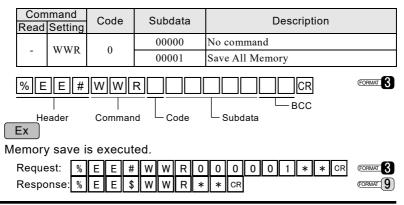
USB Close Function : HLC2_Close()

USB Open Function : HLC2_OpenByIndex(), HLC2_Open()

4-1-8 Save: WWR

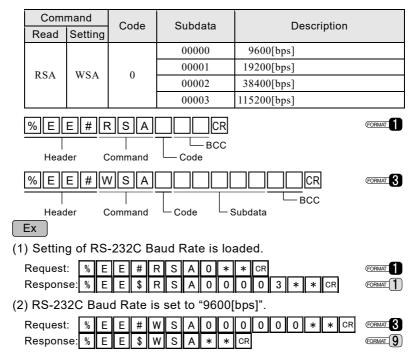
WWR saves the memory.

The command saves all memory.



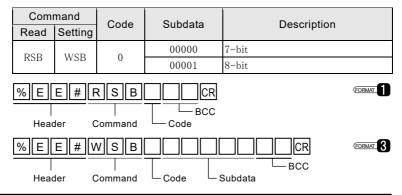
4-1-9 RS-232C Baud Rate: RSA/WSA

WSA and RSA respectively specify and load the setting of baud rate in RS-232C.

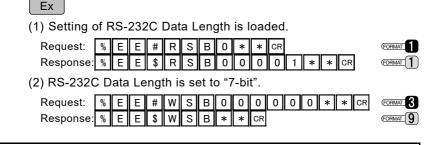


4-1-10 RS-232C Data Length: RSB/WSB

WSB and RSB respectively specify and load the setting of data length in RS-232C.



EORMAT 9

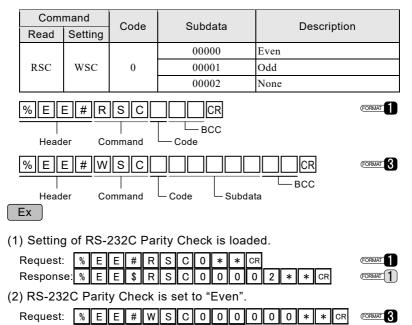


4-1-11 RS-232C Parity Check: RSC/WSC

Response: %

EESW S

WSC and RSC respectively specify and load the setting of parity check in RS-232C communication.



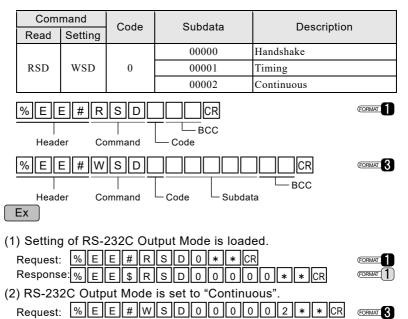
4-7

С

* CR

4-1-12 RS-232C Output Mode: RSD/WSD

WSD and RSD respectively specify and load the setting of output mode in RS-232C communication.



4-1-13 RS-232C Output Type: RSE/WSE

W

S

D

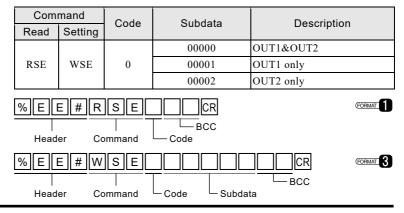
\$

Response: % || E || E |

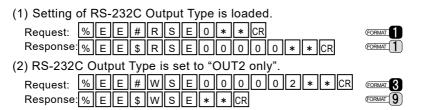
WSE and RSE respectively specify and load the setting of output type in RS-232C communication.

*

EORMAT 9



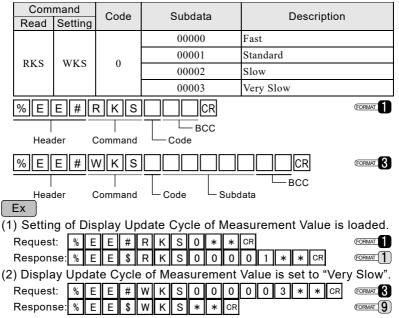
Ex



4-1-14 Display Update Cycle of Measurement Value: RKS/WKS

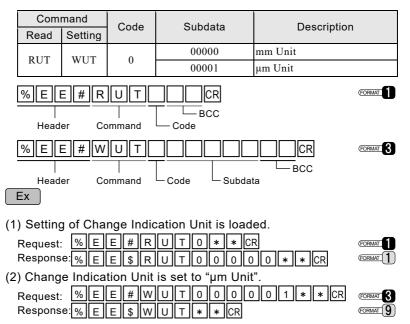
WKS and RKS respectively specify and load the setting of display update cycle of measurement value on the compact console.

The update cycle of measurement value on the compact console is selectable from the four stages of rate.



4-1-15 Change Indication Unit: RUT/WUT

WUT and RUT respectively specify and load the setting of change indication unit of measurement value.

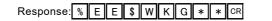


4-1-16 Console Start-up Screen: RKG/WKG

WKG and RKG respectively specify and load the setting of start-up screen on the compact console.

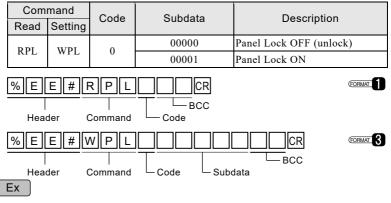
The setting command specifies the screen displayed after the Wake-Up screen on the compact console.

Com	, mand		Subdata								
Read	Setting	Code	Subdata	Description							
			00000	OUT1 Display							
RKG	WKG		00001	OUT1 Operate							
			00002	OUT2 Display							
		0	00003	OUT2 Operate							
			00004	OUT1&2 Display							
			00005	Waveform(A)							
			00006	06 Waveform(B)							
Com Read	mand Setting	Code	Subdata	Description							
			00007	Тор							
	WKG		00008	Setting							
			00009	Head A Menu							
RKG			00010	Head B Menu							
		0	00011	OUT1 Menu							
			00012	OUT2 Menu							
			00013	Common Menu							
			00014	System Menu							
			00015	Measurement Value Menu							
% E	%EE#RKGCCR										
Header Command Code											
% E	E #	WKG			(FORMAT 3						
Header Command Code Subdata											
(1) Setting of Console Start-up Screen is loaded.											
Request: % E E # R K G 0 * * CR											
Response: % E E \$ R K G 0 0 0 * * CR CORMAT											
(2) Console Start-up Screen is set to "OUT1 Operate".											
Request: % E # W K G 0 0 0 1 * * CR @CRMAT 3											



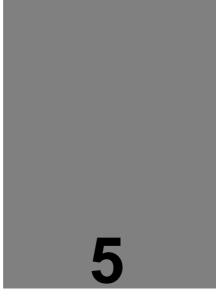
4-1-17 Console Panel Lock: RPL/WPL

 WPL and RPL respectively specify and load the setting of panel lock on the compact console.



(1) Status of Console Panel Lock is loaded.

Request:	%	Е	Е	#	R	Ρ	L	0	*	*	CR				FORMAT
Response:	%	Е	Е	\$	R	Ρ	L	0	0	0	0	0	*	* CR	FORMAT 1
(2) Console Panel Lock is set to "OFF" (unlock).															
Request:	%	Е			W			0	0	0	0	Ó	0	* * CR	(FORMAT 3
Response:	%	Е	Е	\$	W	Ρ	L	*	*	CR					FORMAT 9



Buffering Command

This chapter explains various commands for function settings and execution of operation regarding data buffering.

5-1 Data Buffering Description	·5-2
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5-2-2 Buffering Mode: RBD/WBD	5-11
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RSR/WSR	5-16
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5-1 Data Buffering Description

Buffering is the function that accumulates measurement data to the memory inside the controller and later loads them to external control devices.

The function can temporary accumulate up to 65,000 measurement data to the memory inside the controller before loading them to external control devices such as personal computers. All accumulated data can be loaded later by RS-232C/USB communication control or by the Intelligent Monitor AiM.

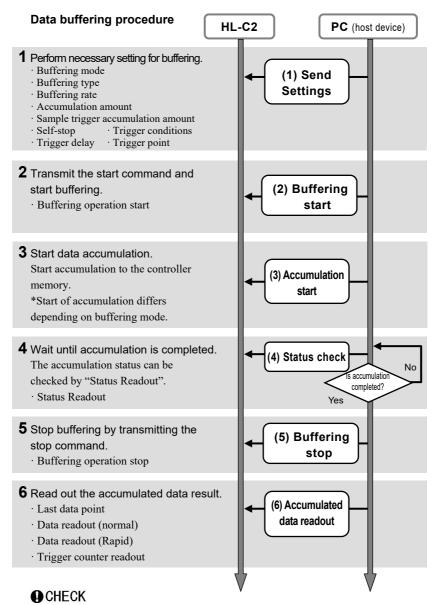
JTECHN I QUE

Use of the Intelligent Monitor AiM (option) is recommended to execute buffering. It makes accumulation and loading of measurement data easy by mouse operation. The measurement data can be saved, replayed and graphically displayed for data check and verification. They also can be saved in the CSV data format.

OCHECK

Programs for buffering must be created by RS-232C/USB communication control. Use the sample program included in "our web site: https://panasonic.net/id/pidsx/global "to try to the basic buffering functions.

Data Buffering Procedures



All the settings related to buffering cannot be changed during the buffering operation. Change the settings after buffering operation stops.

1. Send settings

This process configures the settings of buffering.

1 Select the self-stop.

This function stops the buffering operation automatically at completion of accumulation.

When the Self-stop function is set to ON (buffering operation is automatically stopped), stop input for buffering operation becomes unnecessary. This function is valid when the buffering mode is set to the continuous mode, trigger mode, or sample mode. This function is invalid when the timing mode is selected. When OUT1/OUT2 is set for the buffering type, this function operates immediately after completion of accumulation for OUT1/OUT2. When OUT1&OUT2 is selected, the self-stop function operates at completion of accumulation for both OUT1&OUT2.

(Command description → "5-2-1 Self-stop: RSS/WSS")

2 Select the buffering mode.

Four types of buffering mode can be selected.

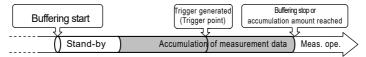
Continuous Mode

- Accumulation to the controller memory starts after buffering operation is initiated.
- The accumulation stops after the specified accumulation amount has been reached or buffering operation is stopped.



Trigger Mode

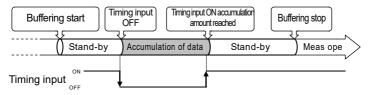
- · When buffering operation starts, the trigger generation is turned to stand-by status.
- The measurement data before and after the trigger point where the trigger is generated is accumulated into the controller memory.
- Accumulation stops when the accumulation amount has reached the setting value or when buffering operation stops.



Timing Mode

- •When buffering operation starts, the timing input is turned to stand-by status.
- Changing the timing input from "ON" to "OFF" during stand-by status starts data accumulation to the controller memory.

• Timing input stops when the accumulation amount has reached the setting value or when buffering operation stops.

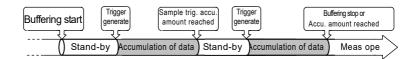


CHECK

Changing the timing input from "ON" to "OFF" again deletes the previous data and starts new data accumulation. Make sure to stop the buffering operation once and load/save the accumulated measurement data before performing the next accumulation.

Sample Trigger Mode

- · When buffering operation starts, the trigger generation is turned to stand-by status.
- · Accumulation of the measurement data for the setting sample trigger accumulation amount starts after the setting trigger condition is generated.
- \cdot After completion of sample trigger accumulation, the trigger generation is turned to stand-by status again.
- (In this case, the status is indicated as "Accumulating".)
- When the setting trigger condition is generated again, accumulation of the setting sample trigger amount starts.
- Accumulation operation stops when the accumulation amount has reached the setting value or when buffering operation stops.



CHECK

Be sure to set the sample trigger accumulation amount so that (accumulation amount) ÷ (sample trigger accumulation amount) is an integer value.

3 Select the buffering type.

This function selects individual data accumulation or simultaneous data accumulation on OUT1 and OUT2.

```
(Command description → "5-2-3 Buffering Type: RTT/WTT")
OUT1 is set as a default.
```

OCHECK

The maximum accumulation data amount differs depending on buffering type.

4 Select the buffering rate.

The rate (interval) of data accumulation to sampling cycle can be adjusted to accumulate the measurement data for long period.

The rate can be selected from "1" (all measurement data) to "1/32768". (When "1/4" is selected, measurement data is accumulated once in four sampling cycles.)

(Command description → "5-2-4 Buffering Rate: RBR/WBR")

Ex The accumulated amount of data in case "OUT1" is specified in the "Buffering Type" with the sampling cycle of 40µs is shown below, depending of the setting in the "Buffering Rate".

1...... 65,000 data can be accumulated within approx. 2.6s. 1/32768 One data is accumulated every 1.3s approximately. Approx. 23 hours of data can be accumulated (max. 65,000 data).

TECHNIQUE

All the measurement data can be accumulated; however, in case that the deviation amount of the measurement data is small to a sampling cycle, setting the data accumulation interval can execute a long-duration data accumulation than measurement at every sampling cycle. This is useful for the effective use of memory since the data accumulation amount is limited.

5 Specify the accumulated amount.

The number of measurement data to be accumulated can be specified.

Specify the data amount to be accumulated from 1 to the Maximum Accumulated Amount.

The maximum accumulated amount varies depending on the setting in "Buffering Type" currently selected.

OUT1 or OUT2 ······Max. accumulated amount = 65,000 data OUT1&OUT2.....Max. accumulated amount = 32,500 data The default is 20.000.

An error occurs if the amount larger than the maximum accumulated amount set in "Buffering Type" is specified.

(Command description + "5-2-5 Accumulated Amount: RBC/WBC")

OCHECK

Accumulation cannot be started when the setting of the range of "accumulation amount" for each "buffering type", settings of "trigger point" and "sample trigger accumulation amount" corresponding with the "accumulation amount" are not correct (out of the setting range).

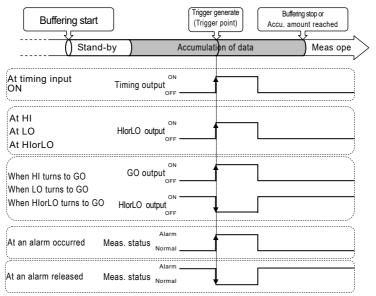
6 Specify the trigger conditions.

This function is used for setting the trigger generation conditions when the buffering mode is set to trigger mode or sample trigger mode.

(Command description **→** "5-2-6 Trigger Conditions: RTR/WTR") The trigger conditions are selectable from "At timing input ON", the results of "judgment output" (HI, LO, HI or LO, HI to GO, LO to GO, HI or LO to GO), "At an alarm occurred", and "At an alarm released". The initial value is set to "At timing input ON".

OCHECK

- Note that the settings of "Upper Limit/Lower Limit Value of Judgment Output" and "Upper Limit/Lower Limit Hysteresis of Judgment Output" become effective when the result of judgment output is set as a trigger condition.
- Note that the setting of "Number of Alarm Delay Times" becomes effective when "At an alarm occurred" is set as a trigger condition.
- Ex) When the "Buffering Mode" is set to trigger mode, the operations of each trigger condition are shown as follows:



CHECK

Normally, the measurement value is on hold at timing input ON status; however, only in the case that the buffering mode is set to trigger mode or sample trigger mode, and this function is set to "At timing input ON", the measurement value is not on hold at timing input ON status during buffering operation.

7 Specify the trigger delay.

This function is used for delaying the timing of trigger detection when the buffering mode is set to trigger mode or sample trigger mode.

(Command description → "5-2-7 Trigger Delay: RTL/WTL")

Sets number of sampling times as the trigger delay value. Setting range is 0 to 100000000.

The status during the trigger delay is indicated as "Accumulating". The initial value is set to "0".

For trigger mode:

Loads the measured data from the actual trigger generated point to the delayed trigger point that has been set for this function.

For sample trigger mode:

Starts accumulation of the measured data from the delayed trigger point that has been set for this function after the trigger was generated. The function ignores even if a new trigger is generated during the trigger delay operation.

OCHECK

When the buffering rate is already set, the trigger delay is counted with the extended sampling in accordance with the setting.

8 Specify the trigger point.

When the buffering mode is set to trigger mode, the measurement data can be loaded by setting the data at the trigger generated as a trigger point.

(Command description → "5-2-8 Trigger Point: RTP/WTP")

Setting range is 1 to setting "accumulation amount".

The initial value is set to "10000".

CHECK

· If the "trigger point" is set to a larger value than the setting "accumulation amount", accumulation cannot be started.

• When the "Trigger Delay" function is set, the measurement data from the trigger delayed data point after the setting trigger is generated can be loaded.

8 Specify the sample trigger accumulation amount.

When the buffering mode is set to sample trigger mode, the sample trigger accumulation amount can be set at every trigger generation.

(Command description → "5-2-9 Sample Trigger Accumulation Amount: RSR/WSR")

Setting range is 1 to setting "accumulation amount". The initial value is set to "1".

CHECK

Be sure to set the sample trigger accumulation amount so that (accumulation amount) \div (sample trigger accumulation amount) is an integer value.

2. Buffering start

Start buffering operation.

(Command description → "5-2-10 Buffering Operation: RBS/WBS")

- **1** Set Buffering Operation to "Start".
 - * The initiation of accumulation differs depending on the buffering mode selected.

3. Accumulation start

Start data accumulation.

The initiation conditions of accumulation differ on the buffering mode selected.

For the initiation conditions of each buffering mode, refer to \rightarrow "5-1-(1) 2. Select the buffering mode."

4. Status check

Wait until accumulation is completed.

Starting conditions of accumulating performance differs on the buffering mode type.

The status of accumulation can be loaded by the "Status Readout" command.

(Command description → "5-2-11 Status Readout: RTS")

Go to Step 5 Buffering Stop without waiting for completion of accumulation.

This function checks the status of the measurement data accumulation.

Use this function for checking the accumulation status before reading the

accumulated data. After having checked the status, the controller replies one of the next status.

Status	Contents
Non-buffering	Buffering operation is not executed at all after turning on the power supply or after initialization, or buffering operation is stopped while waiting for trigger after buffering has started.
Wait for trigger	Wait for trigger status after buffering operation has started.
Accumulating	Buffering operation has started and measurement data is being accumulated, or trigger has being generated and measurement data is being accumulated.
Accumulation completed	Accumulation amount has reached the setting value or the buffering operation has stopped.

5. Buffering stop

Stop buffering operation.

(Command description + "5-2-10 Buffering Operation: RBS/WBS")

Set "Buffering Operation" to "Stop".

Accumulation stops even in the middle of accumulation to the controller memory.

Accumulated data can be loaded after stopping the buffering operation.

CHECK

When the Self-stop function is set to ON (buffering operation is automatically stopped), stop input for buffering operation becomes unnecessary.

6. Accumulated data readout

The accumulated data is read.

Check the status of data accumulation by the "Status Readout" command.
 This checks the accumulation status of measurement data before readout.

Status	Contents
Non-buffering	Buffering operation is not executed at all after turning on the power supply or after initialization, or buffering operation is stopped while waiting for trigger after buffering has started.
Wait for trigger	Wait for trigger status after buffering operation has started.
Accumulating	Buffering operation has started and measurement data is being accumulated, or trigger has being generated and measurement data is being accumulated.
Accumulation completed	Accumulation amount has reached the setting value or the buffering operation has stopped.

(Command description **→** "5-2-11 Status Readout: RTS")

2 Check the final data point.

The status of buffering data accumulation can be loaded as data point.

- "Final Data Point" is set to "0" when the "Status Readout" is set to "Non-buffering".

(Command description \rightarrow "5-2-12 Final Data Point: RLD")

3 Trigger counter readout

When the buffering mode is set to sample trigger mode, the number of times of the final trigger generation can be read out.

(Command description \Rightarrow "5-2-15 Trigger Counter Readout: RLE")

OCHECK

When readout of the trigger counter is performed, stop the data accumulation operation and confirm the "Final Data Point". If the result of "Status Readout" is indicated as accumulation completed and the "Final Data Point" is any values other than "0", readout of the trigger counter can be started.

4 Data Read (normal/rapid)

The accumulated measurement data in the controller memory can be read out. The below shows two reading methods.

Read method	Contents
Normal read	Simply reads the accumulated measurement data as is. (Command description
Rapid read	Reads the accumulated data by the difference from the previous data. Since data with less difference decreases with decreasing variation, the total transmission data amount decreases and the communication time is shortened. (Command description → "5-2-14 Data (rapid): RLB")

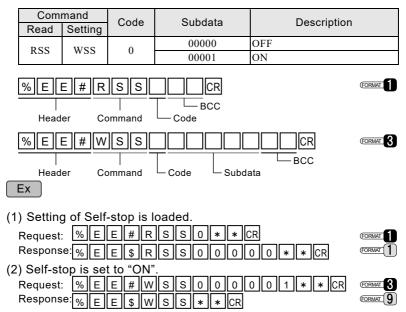
CHECK

To read the buffering data, stop buffering operation and check the "Final Data Point". The accumulated data to the final data point can be read only when the result of "Status Readout" is "Accumulation Completed" and the final data point is the value "other than 0".

5-2 Explanation of Buffering Command

5-2-1Self-stop: RSS/WSS

WSS and RSS respectively specify and load the setting of self-stop.



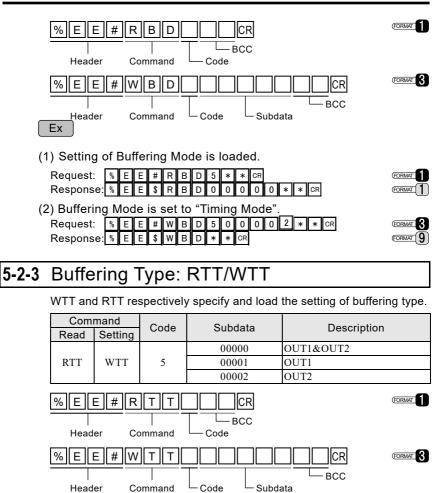
CHECK

When the Self-stop function is set to ON (buffering operation is automatically stopped), stop input for buffering operation becomes unnecessary.

5-2-2Buffering Mode: RBD/WBD

WBD and RBD respectively specify and load the setting of buffering mode.

Com	mand	Code	Subdata	Description				
Read	Setting	Code	Subuala	Description				
			00000	Continuous Mode				
RBD	WBD	5	00001	Trigger Mode				
KDD	WDD	5	00002	Timing Mode				
			00003	Sample Trigger Mode				



(1) Setting of Buffering Type is loaded.

Ex

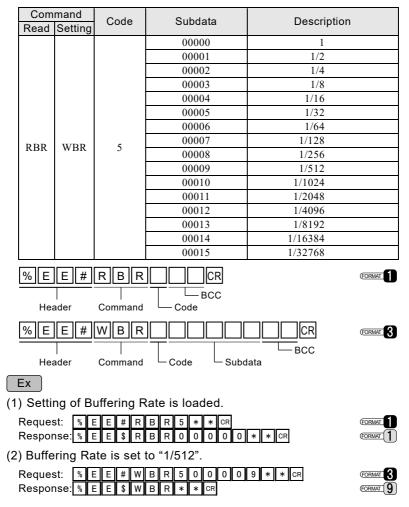
Request:	%	Е	Е	#	R	Т	Т	5	*	*	CR		FORMAT
Response:	%	Ε	Ε	\$	R	Т	Т	0	0	0	0	1 * * CR	FORMAT 1
(2) Buffering	gТ	ур	e i	s s	et	to	"O	UT	2"				
Request:	%	Е	Е	#	W	Т	Т	5	0	0	0	02**CR	(FORMAT 3
Response:	%	Е	Е	\$	W	Т	Т	*	*	CR			FORMAT 9

5-12

5-2-4 Buffering Rate: RBR/WBR

WBR and RBR respectively specify and load the setting of buffering rate.

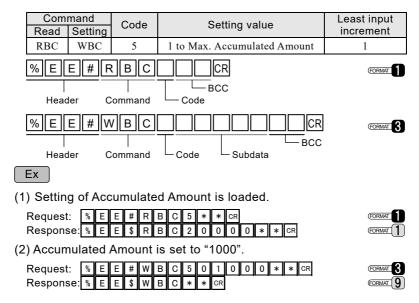
The rate at buffering can be selected from "1" to "1/32768". When "1/4" is selected, data buffering is executed once in four sampling cycles.



5-2-5 Accumulated Amount: RBC/WBC

WBC and RBC respectively specify and load the setting of accumulated amount of data.

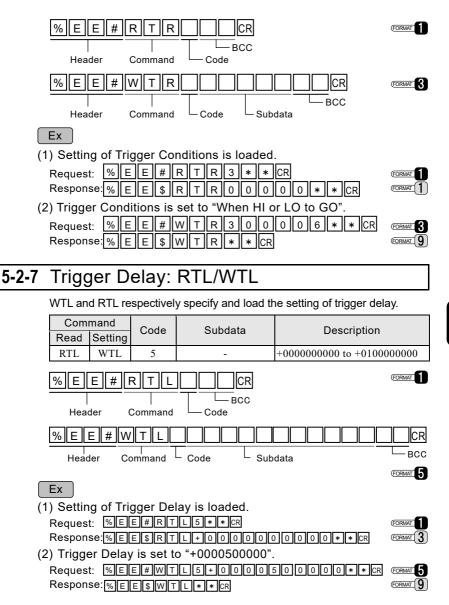
The maximum accumulated amount is 65,000 data when "OUT1" or "OUT2" is selected in Buffering Type, or 32,500 data when "OUT1&OUT2" is selected.



5-2-6 Trigger Conditions: RTR/WTR

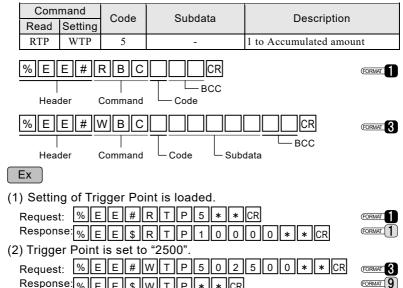
WTR and RTR respectively specify and load the setting of trigger conditions.

Com	mand	Code	Subdata	Description													
Read	Setting	Code	Subuala	Description													
			00000	At timing input ON													
			00001	At HI													
			00002	At LO													
			00003	At HI or LO													
RTR	WTR	3/4	00004	When HI turns to GO													
																00005	When LO turns to GO
			00006	When HI or LO to GO													
			00007	At an alarm occurred													
			00008	At an alarm released													



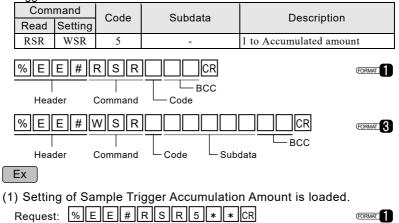
5-2-8 Trigger Point: RTP/WTP

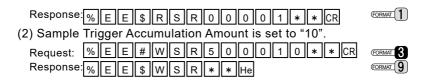
WTP and RTP respectively specify and load the setting of trigger point of data.



5-2-9 Sample Trigger Accumulation Amount: RSR/WSR

WSR and RSR respectively specify and load the setting of sample trigger accumulation amount of data.

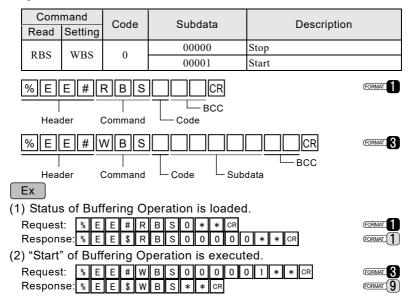




5-2-10 Buffering Operation: RBS/WBS

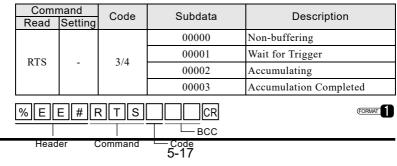
WBS and RBS respectively specify and load the setting of buffering operation.

The conditions for buffering are previously specified before starting buffering operation. Accumulated data can be loaded after stopping the operation.



5-2-11 Status Readout: RTS

RTS loads the status of accumulation.



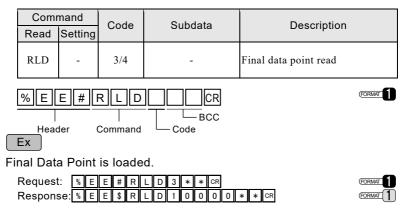
Ex Status Readout setting is loaded. Request: |% E E # R T S 3 * CR 0 * * CR Response: % E E \$ R S 0 Т 0 ٥ 0



5-2-12 Final Data Point: RLD

RLD loads the final data point.

The status of buffering data accumulation can be loaded as data point. The final data point is 0 (zero) when the status is "Non-buffering" or "Wait for Trigger".



5-2-13 Data (normal): RLA

RLA loads the accumulation data by normal readout.

To read the buffering data, stop buffering operation and check the final data point. The accumulated data can be read only when the status is "Accumulation Completed" and the final data point is not "0".

Comr Read		Code	Setting value	Least input increment				
Read	Setting			morement				
RLA	-	3/4	5-digit start point + 5-digit end point 1 to final data point is specified.	1				
% E I Head	E # R	LA ommand	Code Start point End poin					

Ex

Accumulation data is loaded by normal readout.

 Request:
 % E E # R L A 3 0 0 2 0 1 0 0 4 0 0 * * cR
 FORMAT
 COMMAT

 Response:
 % E E \$ R L A + 0 1 2 . 3 4 5 6 7 8 + 0 1 2 .
 3 4 5 6 7 8 + 0 1 2 .
 6 7 8 + 0 1 2 .

5-2-14 Data (rapid): RLB

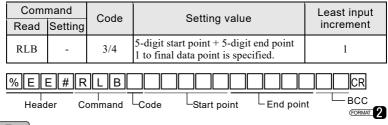
RLB loads the accumulation data by rapid readout.

To read the buffering data, stop buffering operation and check the final data point. The accumulated data can be read only when the status is "Accumulation Completed" and the final data point is not "0". The data of specified head point is stored with the head data format shown below. For the data of second point and subsequent points, the differential by the previous data (the data based on the 6 places of decimals) is responded.

Head data format

1-character symbol + 3-digit integral part (no zero suppress)

+ decimal point + 6-digit decimal part



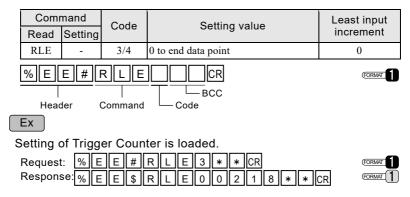
Ex

Accumulation data is loaded by rapid readout.

Request: 🔏	Е	Е	#	R	L	В	3	0	0	2	0	1	0	0	4	0	0	*	*	CR	(FORMAT 2
Response:	Е	Е	\$	R	L	В	+	0	1	2		3	4	5	6	7	8	+	1	2	3 -
2	2	5	+	7	6		+	2	3	-	5	9	+	3	+	7	8	*	*	CR	FORMAT 7

5-2-15 Trigger Counter Readout: RLE

RLE loads the number of times of the trigger generation.



Appendix

This chapter describes index and revision history.

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Revision history

Released date	Revision No.
October 2007	First release
May 2008	Second release
July 2008	Third release
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September 2009	Fifth release
June 2010	Sixth release
February 2011	Seventh release
December 2012	Eighth release
June 2013	Ninth release
January 2019	Tenth release

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